



**Article Title: Implementation of Deep Learning Technique for Accurate Land Cover Classification**

# Implementation of Deep Learning Technique for Accurate Land Cover Classification

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## ABSTRACT

Detecting and modelling Land Cover are crucial for managing natural resources, assessing environmental impacts, and preserving ecological connectivity. Convolutional Neural Networks (CNNs) have become pivotal in advancing remote sensing applications, particularly in land cover classification. Therefore, this study introduces a CNN classifier for the prediction land cover efficiently. The preprocessing is carried out based on Principle Component Analysis (PCA), which reduces the dimensionality of the input data while retaining essential information. This step aims to enhance computational efficiency and improve the CNN's ability to extract relevant features during training. Following preprocessing, a comprehensive training phase involves optimizing the CNN architecture using a labelled dataset. This process allows the network to learn intricate spatial patterns and spectral characteristics crucial for accurate land cover classification. Evaluation of the trained model occurs in the testing phase, where performance metrics such as accuracy, precision, recall, and F1-score are computed using an independent validation dataset. Results obtained from the python software demonstrate that the CNN-PCA framework's capability to achieve high classification accuracy across diverse land cover types.

**Keywords:** Land Cover, Convolutional Neural Networks, Principle Component Analysis, Python software.

## 1 Introduction

Detecting and modelling Land Cover are essential tasks that underpin various aspects of natural resource management, environmental assessment, and ecological connectivity preservation [1-2]. Accurate detection allows to understand how land is being utilized and its impact on ecosystems, biodiversity, and climate. This knowledge is crucial for making informed decisions regarding sustainable development, conservation efforts, and disaster risk management [3-4]. Preprocessing is a necessary step in Land cover analysis to enhance the quality of input image and improve the effectiveness of subsequent classification tasks. It involves techniques such as image enhancement, noise reduction, geometric correction, and feature extraction [5-6]. Methods like histogram equalization or contrast stretching improve the visual quality of images by adjusting pixel intensities across the entire spectrum. This



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enhancement can reveal details in dark or bright regions, enhancing interpretability [7]. Techniques such as median filtering or Gaussian smoothing eliminate or mitigate noise, which distort image features and affect classification accuracy. Filtering operations help preserve relevant spatial and spectral information while reducing unwanted artifacts. Each preprocessing technique offers distinct advantages in preparing data for classification [8]. Image enhancement improves visual clarity, noise reduction enhances data integrity, geometric correction ensures spatial accuracy, and feature extraction emphasizes relevant information [9]. However, these methods can also introduce challenges. Enhanced images may become overly processed, noise reduction might over smooth subtle details, geometric correction could introduce registration errors, and feature extraction may overlook context-specific nuances [10].

Henceforth, the PCA is utilized to further enhance data quality and reduce dimensionality, thereby improving computational efficiency and aiding in feature selection for classification tasks. PCA transforms the original image bands into principal components that capture the maximum variance in the data while minimizing redundancy. This transformation simplifies subsequent classification processes by focusing on the most informative features, potentially enhancing classification accuracy and interpretability. Classification follows preprocessing and involves categorizing pixels or image segments into predefined land cover classes. This step allows us to map and quantify different land uses and covers across a landscape. Conventional classifiers include Support Vector Machines (SVMs), Random Forests, and Decision Trees [11-12]. SVMs excel in handling complex datasets and are effective for binary classification tasks. Random Forests offer robustness to noise and over fitting while Decision Trees provide interpretability of classification rules. However, SVMs can be computationally intensive, Random Forests may struggle with class imbalance, and Decision Trees may over fit noisy data [13-15]. In order to overcome the above said limitations, the proposed work employs the Deep Learning based CNN classifier is employed for effectual prediction accuracy. The objectives of the proposed work is expressed as follows,

- To accurately predict and monitor land cover dynamics, supporting sustainable development and environmental stewardship efforts globally.
- To dimensionality reduction by retaining only the most informative component with the aid of PCA based preprocessing.
- To accurately classify land cover types based on spectral information extracted from remote sensing imagery, the CNN model is developed.

## **2 Proposed Methodology**

Accurate land cover classification plays a pivotal role in various fields such as environmental monitoring, urban planning, agriculture, and natural resource management. Traditional methods of land cover classification often rely on manually crafted features and lack the ability

The diagram illustrates the CNN architecture for image classification. It starts with an **INPUT IMAGE** (a noisy image with red and blue features) which undergoes **PREPROCESSING USING PCA**. The preprocessed data is then split into **TRAINING DATA** and **TESTING DATA**. The training data is used to train the **CNN CLASSIFIER**, which consists of several layers: **INPUT FEATURE MAPS** ( $C_1$ ), **FEATURE MAPS** ( $S_1$ ), **FEATURE MAPS** ( $C_2$ ), **FEATURE MAPS** ( $S_2$ ), and **FEATURE MAPS** ( $C_3$ ). The output is **S<sub>3</sub> OUTPUT**. The architecture also includes **CONVOLUTION**, **POOLING**, **FEATURE EXTRACTION**, and **CLASSIFICATION** steps. The testing data is used to evaluate the classifier's performance.

The block diagram represents the process of land cover prediction using PCA and CNN classifier. Initially, a hyper spectral image is provided as the input data, capturing detailed spectral information across various wavelengths. This input data undergoes preprocessing using PCA. PCA is a dimensionality reduction technique that extracts the most significant features from the data while removing noise, thereby making the data more manageable for further processing. Following the preprocessing step, the data is divided into training and testing datasets. The training data is used to train the CNN classifier, which is designed to learn and recognize different land cover types from the pre-processed features. The trained CNN classifier is then validated and tested using the testing data to evaluate its performance and accuracy in predicting land cover types. Overall, this process integrates PCA for effective data preprocessing and a CNN classifier for robust land cover prediction, ensuring accurate and efficient analysis of hyper spectral images.

PCA is a powerful technique used in various fields, including remote sensing and land cover prediction, to reduce the dimensionality of data while preserving important information. PCA is effective for preprocessing in land cover prediction as it reduces multi collinearity among spectral bands, identifies key components of variance, and facilitates improved modelling by focusing on the most informative features.



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### Input image

Assume you have a dataset where each sample (or pixel) is represented by multiple features (e.g., spectral bands from satellite imagery).

### Data Scaling

Normalize or standardize your data to ensure that each feature contributes equally to the analysis. PCA is sensitive to the scale of the input features, so it's crucial to scale them appropriately.

PCA starts with computing the covariance matrix of the cantered data. Let's denote the data matrix as  $XXX$ , where each row represents a sample and each column represents a feature.

$$Cov(X) = \frac{1}{n-1} X^T X \quad (1)$$

Perform eigenvalue decomposition of the covariance matrix to find its eigenvectors and eigenvalues.

$$Cov(X)v = \lambda v \quad (2)$$

Where  $\lambda$  is an eigenvalue and  $v$  is the corresponding eigenvector.

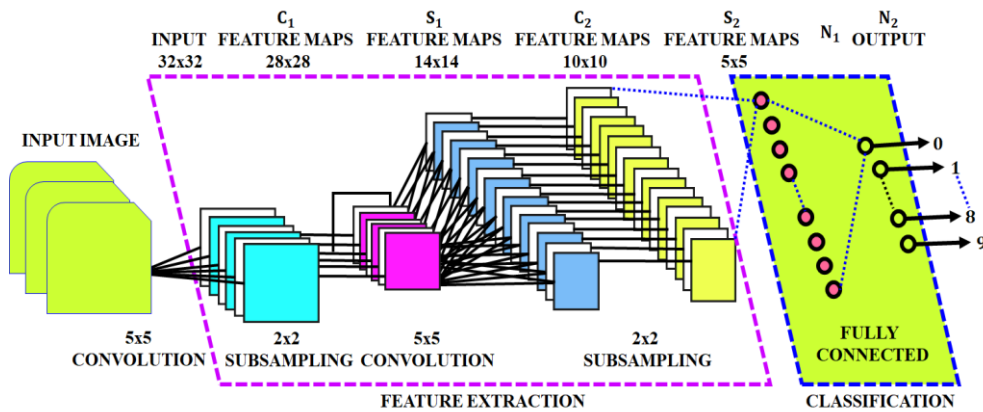
Rank the eigenvectors based on their corresponding eigenvalues in descending order. The eigenvectors with the largest eigenvalues (principal components) capture the most variance in the data. Project the original data onto the new feature space defined by the selected principal components.

## 2.2 Classification Using CNN

CNNs are highly effective for land cover classification from satellite imagery due to their ability to automatically learn spatial hierarchies of features. The CNN architecture typically consists of convolutional layers that extract spatial features from input images, followed by pooling layers that down sample the feature maps to reduce dimensionality while retaining important spatial information. These layers are often interleaved with activation functions like ReLU to introduce non-linearity and improve model performance. For land cover prediction, the final layers of the CNN are fully connected, leading to a softmax layer that outputs class probabilities. Training a CNN involves feeding it with labelled satellite image patches, optimizing using back propagation and an appropriate loss function (e.g., categorical cross-entropy), and validating its performance on a separate test set. Fine-tuning with techniques like data augmentation and transfer learning can further enhance the CNN's ability to generalize across different geographic regions and varying environmental conditions, making it a robust tool for accurate land cover classification tasks.



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**Figure 2:** Architecture of CNN classifier

Equations (3) and (4) show how the 1D convolutional layer works.

$$x_k = b_k + \sum_{i=1}^N (s_k, w_{ik}) \quad (3)$$

$$y_k = f(x_k) \quad (4)$$

Equation (6) indicates the pooling layer's input, which is the convolutional layer's output. The output values of convolutional layer are included in region  $\mathfrak{R}$ , from which we take the maximum value. The output of the max-pooling layer is  $s_k$ .

$$f_{(x_k)} = \max(0, x_k) \quad (5)$$

$$s_k = \max_{i \in \mathfrak{R}} y_k \quad (6)$$

| Layer           | Output Volume | Description                                                              |
|-----------------|---------------|--------------------------------------------------------------------------|
| Input           | M,1,80        |                                                                          |
| Conv1D-1        | 100,1,71      | Number of filters:100,Kernal size:1×10,Activation:ReLU                   |
| Dropout         | 100,1,71      | Gaussian dropout:0.3                                                     |
| Pool            | 100,1,35      | Maxpooling1D:2×2                                                         |
| Conv1D-2        | 50,1,36       | Number of filters:50,Kernal size:1×10,Activation: ReLu                   |
| Dropout         | 50,1,26       | Gaussian dropout:0.3                                                     |
| Pool            | 50,1,13       | Maxpooling1D:2×2                                                         |
| Dense_CNN       | n             | Fully connected n units,Activation:Softmax                               |
| MLP-1           | 100,1,80      | Number of nodes:100, Activation: ReLu                                    |
| Dropout         | 100,1,80      | Gaussian dropout:0.3                                                     |
| MLP-1           | 50,1,80       | Number of nodes:50, Activation: ReLu                                     |
| Dropout         | 50,1,80       | Gaussian dropout:0.3                                                     |
| Dense_DNN       | n             | Fully connected n units,Activation:Softmax                               |
| Softmax Average | n             | Average:[Dense_CNN,Dense_CNN]Fully connected n units activation: Softmax |



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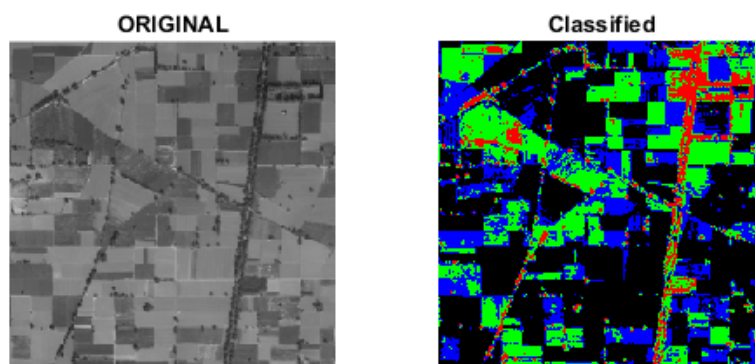
### 3 Results and Discussion

Implementing PCA-based preprocessing in conjunction with deep learning techniques represents a powerful approach for accurate land cover classification from satellite imagery. PCA aids in reducing the dimensionality of high-dimensional spectral data while preserving important variance, thereby enhancing computational efficiency and reducing over fitting risks in subsequent deep learning models. The DL based CNN is employed to achieve robust and precise land cover classification outcomes essential for environmental monitoring. The proposed work is implemented in MATLAB/Simulink for validating the developed work.



**Figure 3:** *Input image*

The Input image shows a diverse landscape with a clear distinction between urban and rural land cover. The urban areas are densely built-up with significant infrastructure, while the rural areas are characterized by agricultural fields and open spaces. The mixed-use areas likely support a range of activities, contributing to the economic and social fabric of the region.



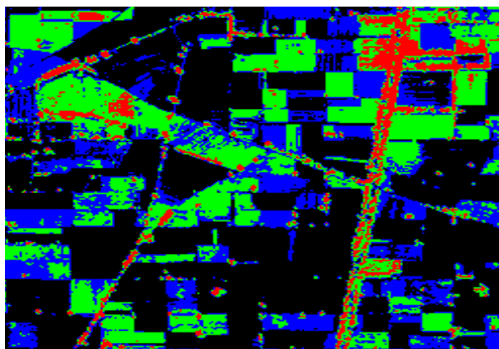
**Figure 4:** *Original and classified image*

The original grayscale image depicts agricultural fields with structured patterns, roads, and possible vegetation areas. The classified image provides a color-coded representation: green for vegetation or crops, blue for water bodies or wetlands, red for urban or built-up areas, and



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black for barren or non-vegetated land. This classification helps in distinguishing different land cover types efficiently.



**Figure 5:** Output image using CNN classifier

The classified image, processed using a CNN classifier, provides a color-coded breakdown: green indicates vegetation or crops, blue denotes water bodies or wetlands, red marks urban or built-up areas, and black represents barren or non-vegetated land. This classification highlights various land cover types effectively, aiding in landscape analysis and planning.

**Table 1:** Comparison of Accuracy

| Classifier techniques | Accuracy (%) |
|-----------------------|--------------|
| RF                    | 90.51        |
| SVM                   | 91.21        |
| ANN                   | 92.34        |
| Proposed CNN          | 94.34        |

The proposed CNN classifier is compared with the conventional ML classifiers for showing the importance of the developed work, from the table 1 it is evident that the CNN classifier attains high accuracy of 94.34% compared to the others.

#### 4 Conclusion

The integration of PCA-based preprocessing with deep learning techniques offers a compelling strategy for enhancing the accuracy of land cover classification from satellite imagery. PCA based preprocessing effectively reduces the dimensionality of spectral data while retaining essential variance, thereby optimizing the input for subsequent deep learning models such as (CNNs). By focusing on the most informative components extracted by PCA, CNNs efficiently learn and recognize complex spatial patterns inherent in land cover types. This combined approach not only improves computational efficiency but also enhances the model's ability to generalize across diverse geographic regions and environmental conditions. The MATLAB is employed to validate the performance of the proposed system and the comparative analysis proved that the proposed CNN classifier has high accuracy of 94.34% compared to the



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conventional topologies. Ultimately, DL based CNN classifier represents a robust framework capable of delivering accurate and reliable land cover classification results, crucial for various applications in environmental science, urban planning, and resource management.

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